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Stochastic Hydrology

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Course Introduction

- Why stochastic hydrology?
- Course content
- Some definition from system's theory

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Why stochastic hydrology?

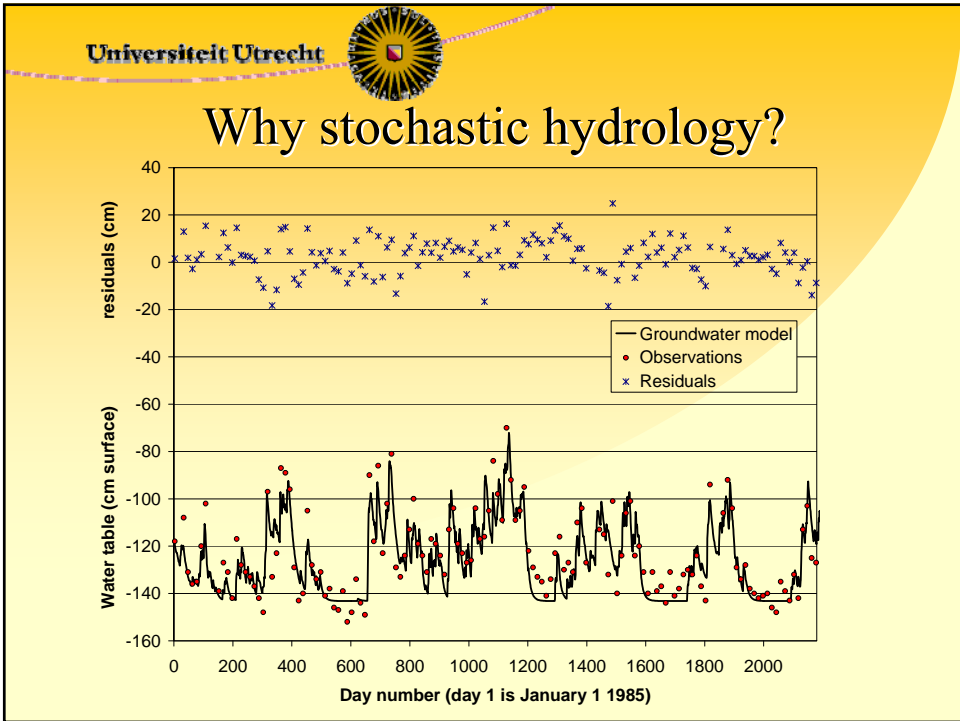
Stochastic derives from στοχαστικός <στοχάζεσθαι <στόχος (target)



To aim for the truth



To imagine, think deeply,
bethink, contemplate

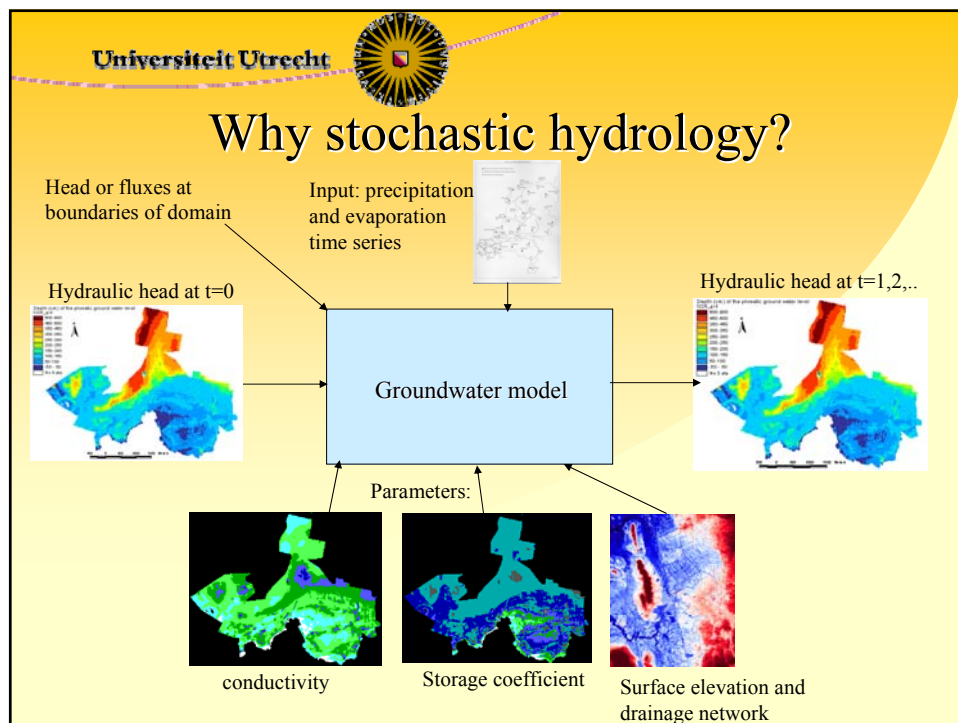



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Why stochastic hydrology?

What causes these differences?

- Observation errors
- Errors in boundary conditions, initial conditions and input
- Unknown heterogeneity and parameters
- Scale discrepancy
- Model errors

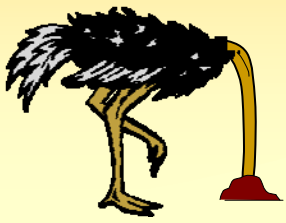


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Why stochastic hydrology?


There are two ways of dealing with model residuals

Deterministic hydrology



Stochastic hydrology



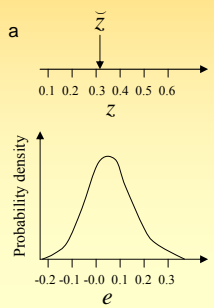
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Why stochastic hydrology?

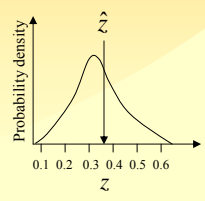
Dealing with model residuals


$$Z = \tilde{z} + E$$

a



b

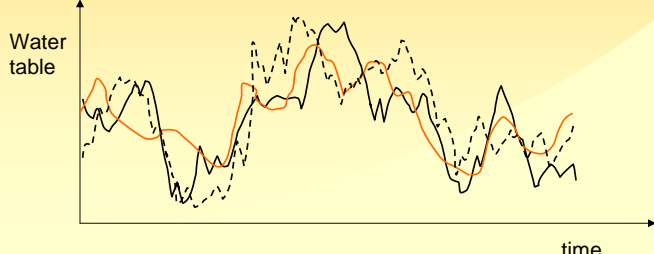



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Why stochastic hydrology?

The advantages of using stochastic models

1. Models are smooth; reality messy and rugged



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Why stochastic hydrology?

The advantages of using stochastic models

2. $\hat{z} \neq \tilde{z}$ for non-linear models

The optimal prediction (with the smallest expected error) is *not* the same as the outcome of the deterministic model!

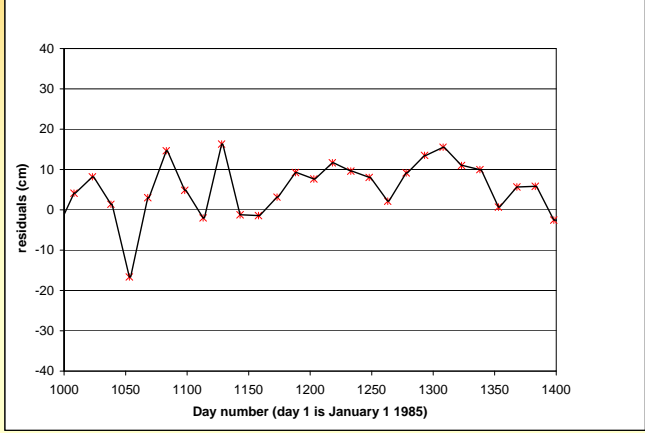
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Why stochastic hydrology?

The advantages of using stochastic models

3. Residuals contain information



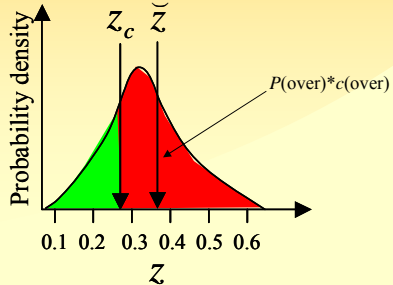
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Why stochastic hydrology?

The advantages of using stochastic models

4. Better decisions because of accounting for uncertainty



Clean up only if : costs cleanup < $p(\text{over}) * c(\text{over})$



Why stochastic hydrology?

The advantages of using stochastic models

5. Monitoring design

Maximise accuracy given a fixed budget

Minimise costs given a required accuracy



Why stochastic hydrology?


The advantages of using stochastic models

6. Investing to improve accuracy

$$r = p + q_v - e - d - \Delta su - \Delta g - \Delta so$$

$$\sigma_r^2 = \sigma_p^2 + \sigma_{q_v}^2 + \sigma_e^2 + \sigma_d^2 + \sigma_{\Delta su}^2 + \sigma_{\Delta g}^2 + \sigma_{\Delta so}^2$$


By tackling the largest error sources first!

Universiteit Utrecht  **Course content**

Program (SUBJECT TO CHANGE)


GEO4-4420: STOCHASTIC HYDROLOGY

Day	Date	Start	Finish	Building	Room	Work form	Topics
week 7							
Mon	2/15/2010	13:15	17:00	UNNIK	027 -ZV	Lecture	Introduction
Thu	2/18/2010	9:30	12:45	UNNIK	027 -ZV	Lecture	Random variables
week 8							
Mon	2/22/2010	13:15	17:00	UNNIK	027 -ZV	Lecture	Hydrological statistics
Thu	2/25/2010	9:30	12:45	UNNIK	422	CPR	Hydrological statistics
week 9							
Mon	3/1/2010	13:15	17:00	UNNIK	027 -ZV	Lecture	Random functions
Thu	3/4/2010	9:30	12:45	UNNIK	027 -ZV	Lecture	Random functions
week 10							
Mon	3/8/2010	13:15	17:00	UNNIK	027 -ZV	Lecture	Gaostatistics
Thu	3/11/2010	9:30	12:45	UNNIK	027 -ZV	Lecture	Gaostatistics
week 11							
Mon	3/15/2010	13:15	17:00	UNNIK	027 -ZV	Lecture	Time series analysis
Thu	3/18/2010	9:30	12:45	UNNIK	027 -ZV	Lecture	Time series analysis
week 12							
Mon	3/22/2010	13:15	17:00	UNNIK	027 -ZV	Lecture	Forward stochastic modelling
Thu	3/25/2010	9:30	12:45	UNNIK	422	CPR	Gaostatistics
week 13							
Mon	3/29/2010	13:15	17:00	UNNIK	027 -ZV	Lecture	The Kalman filter
Thu	4/1/2010	9:30	12:45	UNNIK	027 -ZV	Lecture	Data-assimilation
week 14							
Thu	4/8/2010	9:30	12:45	UNNIK	027 -ZV	Lecture	Presentation research proposals
week 15							
Mon	4/12/2010	13:15	16:00	UNNIK	027 -ZV	Exercise	Exercising old exams
Thu	4/15/2010	9:30	12:30	UNNIK	027 -ZV	Exam	Exam

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Special topics:


- Sampling and monitoring
- Inverse estimation
- Ordinary stochastic differential equations
- Point processes
- Upscaling and downscaling methods
- Uncertainty and decision making

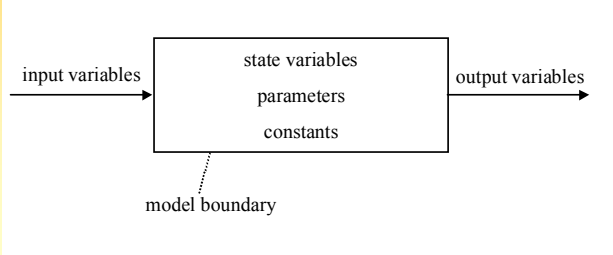
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Grading

- Exam 80%,
- Research proposal 10%,
- presentation of research proposal 10%.

Grades in one decimal are given for the Exam, grades in half points are given for the proposal and presentation. The average grade is rounded to two decimals. An average grade of 5.50 and higher means passing the course (5.49 is failing).

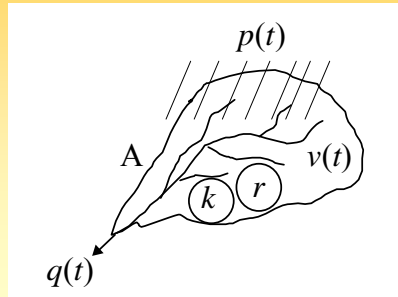
Universiteit Utrecht  Some definitions from system's theory



The diagram illustrates a system model. A central rectangular box represents the system, containing the text "state variables", "parameters", and "constants". An arrow labeled "input variables" points into the left side of the box. An arrow labeled "output variables" points out from the right side of the box. A dotted line labeled "model boundary" points to the bottom edge of the box.



Some definitions from system's theory



$$v(t) = v(t-1) + \{A \cdot [p(t) - r] - q(t)\} \Delta t$$

$$q(t) = kv(t)$$

$$v(t) = [1 - k\Delta t] \cdot v(t-1) + A \cdot [p(t) - r] \Delta t$$